

## Q-Motion® Servo Controller, 3 Axes

For Piezoelectric Inertia Drives, TCP/IP, USB Interface



### E-873.3QTU

- Broadband encoder input
- Macro programmable for stand-alone functionality
- Fast startup due to ID chip detection
- Data recorder
- Digital I/O ports (TTL)
- Digital joystick for manual operation

#### Digital servo controller for piezo inertia drives

Integrated power amplifier and voltage generator for piezo inertia drives. Point-to-point motion, trapezoidal velocity profile, actuator mode for nanometer precision positioning at the target position. 3 axes.

#### Encoder inputs

Differential signal transmission for analog (sin/cos) encoder signals. Input for TTL signals for reference point switches.

#### Interfaces

USB and TCP/IP for commanding. I/O lines (digital) for automation. Connection for digital joystick.

#### Extensive functions, software support

Powerful macro command language. Nonvolatile macro storage, e.g., for stand-alone operation with autostart macro. Data recorder. ID chip detection for fast startup. PID controller, parameter changing during operation. Extensive software support, e.g., for NI LabVIEW, C, C++, MATLAB, Python. PIMikroMove user software.

## Specifications

| E-873.3QTU                         |   |
|------------------------------------|---|
| Function                           | Q-Motion® controller for positioning systems with piezo inertia drives, benchtop device with option for control cabinet mounting  |
| Axes                               | 3   |
| Supported functions                | Point-to-point motion. Startup macro. Data recorder for recording operating data such as motor voltage, position or position error. Internal safety circuitry: Watchdog timer. ID chip detection. |
| Motion and control                 |   |
| Controller type                    | PID controller, parameter changing during operation   |
| Encoder input                      | Analog encoder inputs sine-cosine, interpolation selectable to 20000. Interpolation electronics preset for differential transmission, 1 V <sub>pp</sub> and 2.5 V encoder offset signal.          |
| Stall detection                    | Automatic motor stop  |
| Input reference point switch       | 1 × TTL for integrated reference in the encoder   |
| Electrical properties              |   |
| Max. output power                  | 30 W per axis   |
| Output voltage                     | 0 to 100 V, drive-dependent selection   |
| Interfaces and operation           |   |
| Communication interfaces           | TCP/IP, USB   |
| Motor / sensor connection          | 3 × Sub-D 15 (f)  |
| I/O lines                          | 4 digital inputs, 4 digital outputs   |
| Command set                        | PI General Command Set (GCS)  |
| User software                      | PIMikroMove   |
| Application programming interfaces | API for C / C++ / C# / VB.NET / MATLAB / Python, drivers for NI LabVIEW   |
| Manual control (optional)          | USB joystick  |
| Miscellaneous                      |   |
| Operating voltage                  | 24 V from external power adapter (in the scope of delivery)   |
| Max. current consumption           | 5 A   |
| Operating temperature range        | 0 to 50 °C  |
| Mass                               | 1.7 kg  |
| Dimensions                         | 312 mm x 153.4 mm x 59.2 mm (incl. mounting rails)  |

Ask about customized versions.

## Ordering Information

### E-873.3QTU

Q-Motion® controller for piezoelectric inertia drives, 3 axes, benchtop device (industry), TCP/IP, USB, I/O, joystick